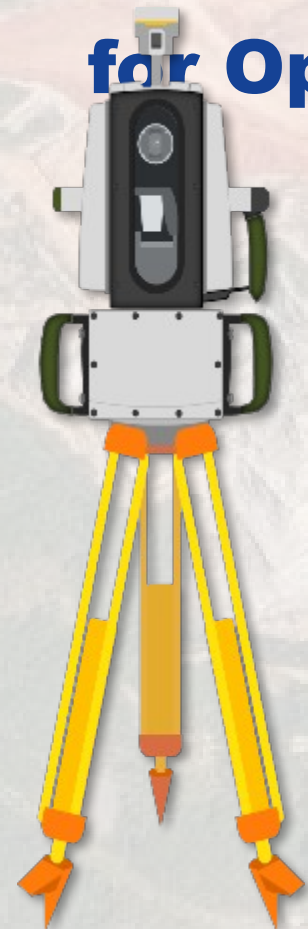


Absolute Accuracy Improvement of **UAV**

Photogrammetric Point Clouds using **TLS-Derived Cloud**

Ground Control Points (**CGCPs**)

for Open-Pit



Mr. Boonyarit Keawara

reying (**C**
ine, Thai



Mr. Thanatepol Boonprakob

Mae Moh Coal



Electricity Generating Authority of



30 KM²

MINING AREA

2 KM² / MONTH

ACTIVE MINING

AREA



**1.1 MILLION
TONS / MONTH**

COAL PRODUCTION

**6.2 MILLION
CUBIC METERS /
MONTH**

WASTE REMOVAL



EGAT



CONTRACTOR

**9.3 MILLION €
/ MONTH**

CONTRACTORS

PAYMENT



UNIT EXCAVATION COST
COAL ≈ 1.05 € / TON
WASTE ≈ 1.3 € / CUBIC METERS

PROBLEM & CHALLENGE

Ministry Laser Scanner (TLS) : Maptek 3
Lose \approx 60 hours of excavation times / month
I-site XR3
can obstruct the line of sight

- Relocate the scanning position during scanning for several times
- Stop machinery to achieve full area coverage.

Camera resolution: 20 MP

Accuracy 5 mm @ 65 m



The potential of UAV

High Altitude

Low Altitude

UAV with camera



Data Coverage:

Time Efficiency:

Operation Continuity:

Absolute Accuracy:

Point-Cloud Fidelity:

UAV with LiDAR



Data Coverage:

Time Efficiency:

Operation Continuity:

Absolute Accuracy:

Point-Cloud Fidelity:

Large area coverage

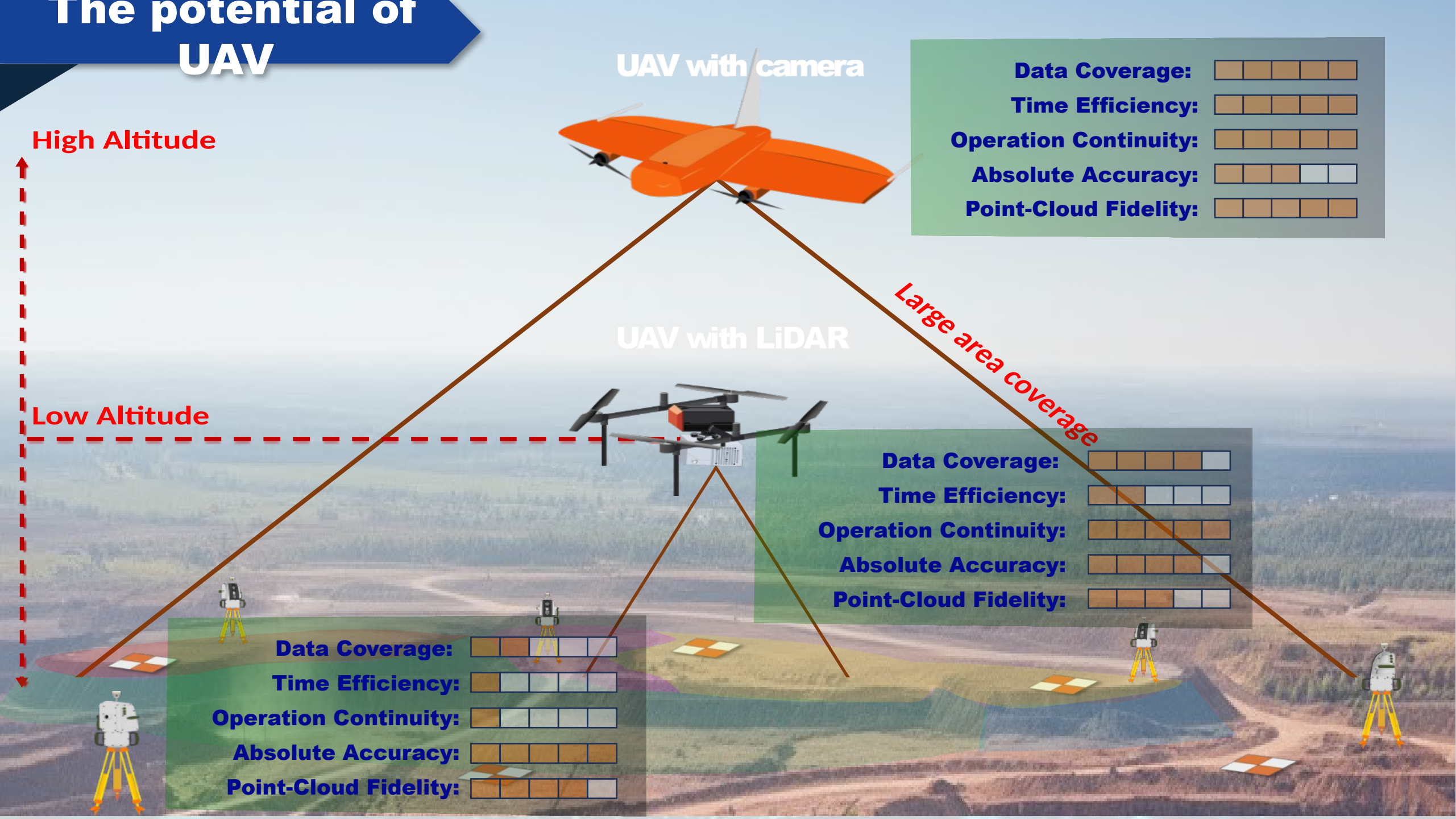
Data Coverage:

Time Efficiency:

Operation Continuity:

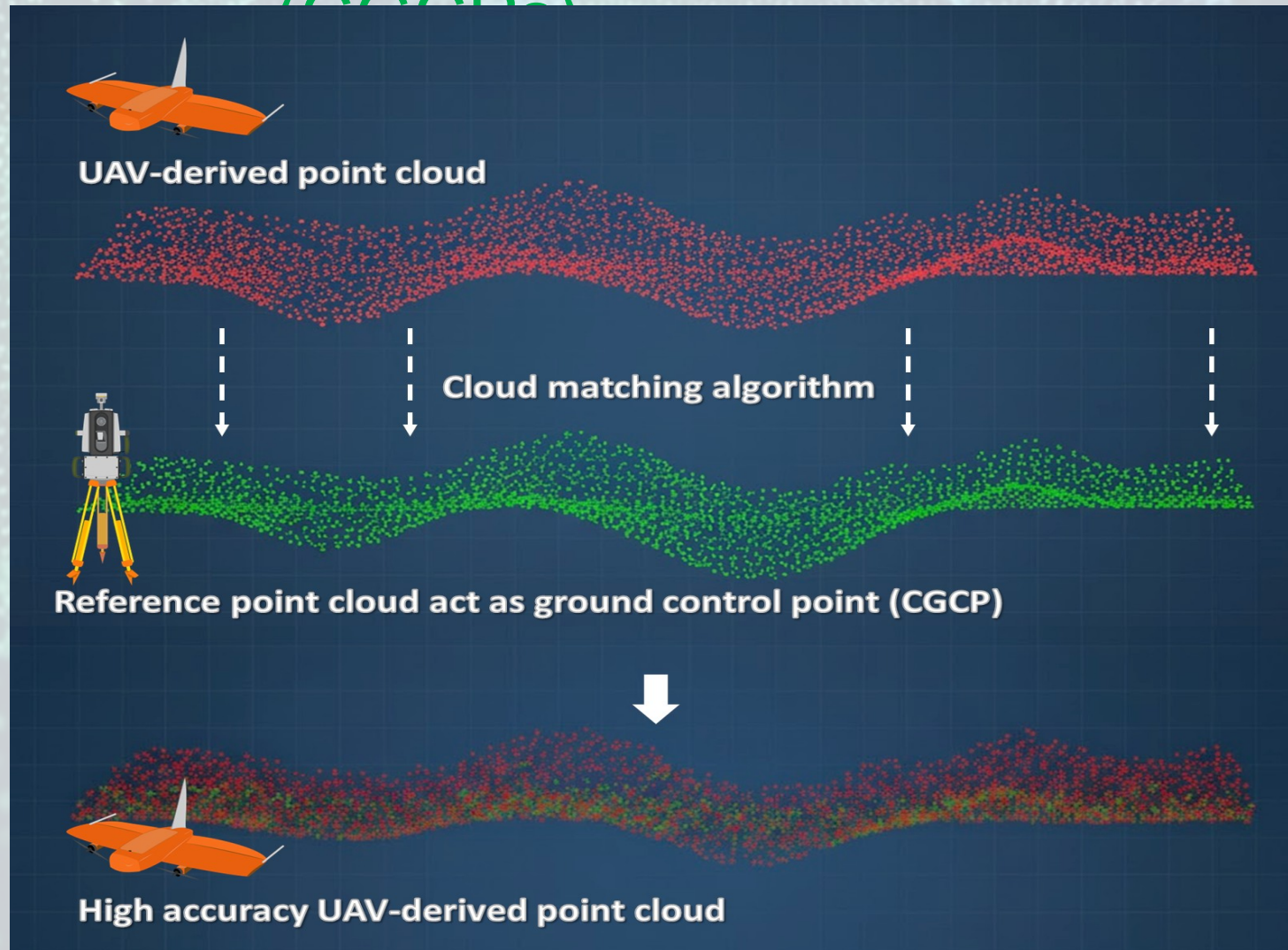
Absolute Accuracy:

Point-Cloud Fidelity:



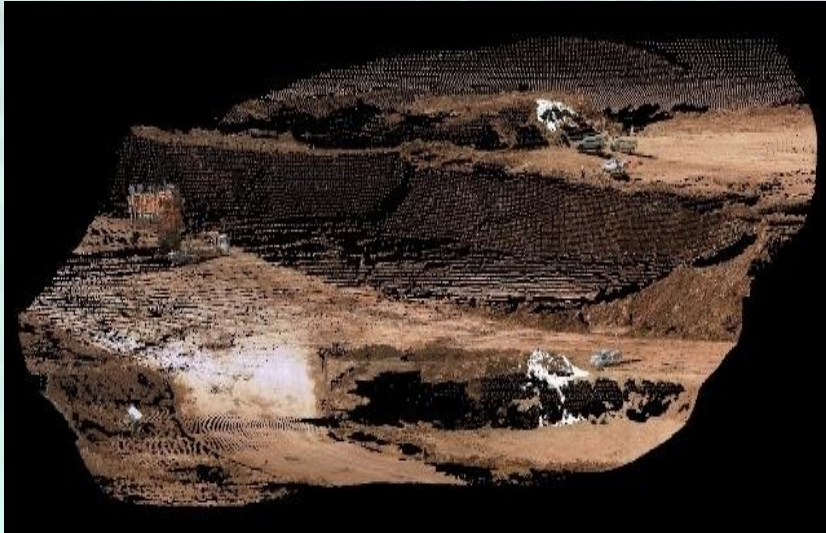
GCP-free solution

TLS-Derived Cloud Ground Control Points (CGCP)

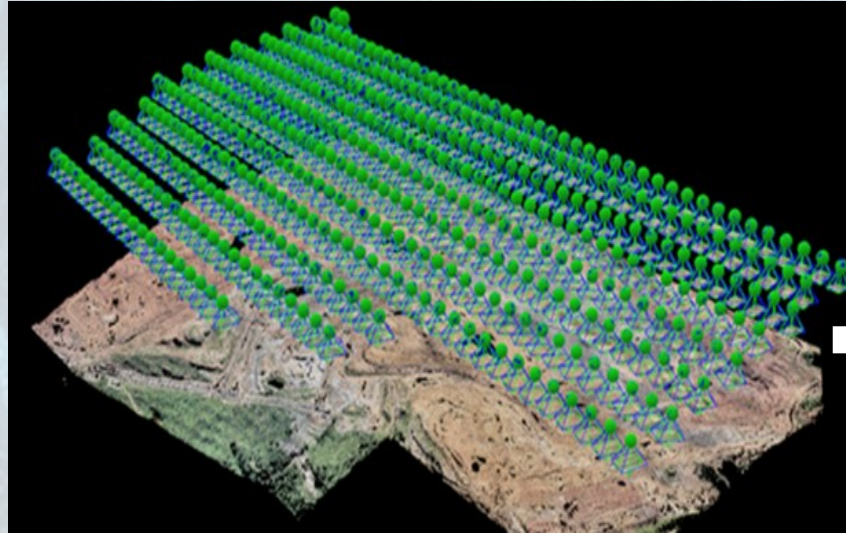


Point Cloud processing

TLS Point Cloud Processing



UAV Point Cloud Processing



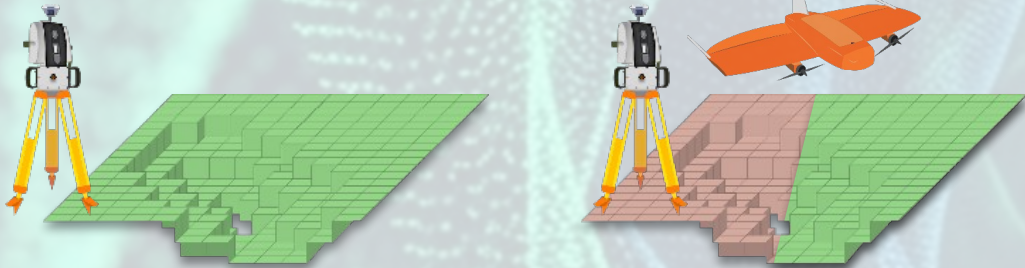
27 independent survey plots



- **Unwanted data** (such as vehicles, excavators, and conveyors) is filtered out.
- The filtered UAV point cloud is clipped to match the TLS's boundary for consistency.
- **Global registration** is performed using a Cloud-to-Cloud registration.
- **Selective data integration** is executed to merge the datasets effectively.
- The resulting point cloud can be utilized across **various applications**.

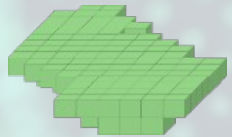
Comparative Assessment

Initial Surface



TLS Surface

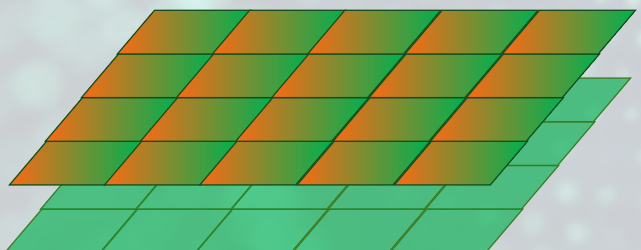
UAV Surface



TLS Volume

UAV Volume

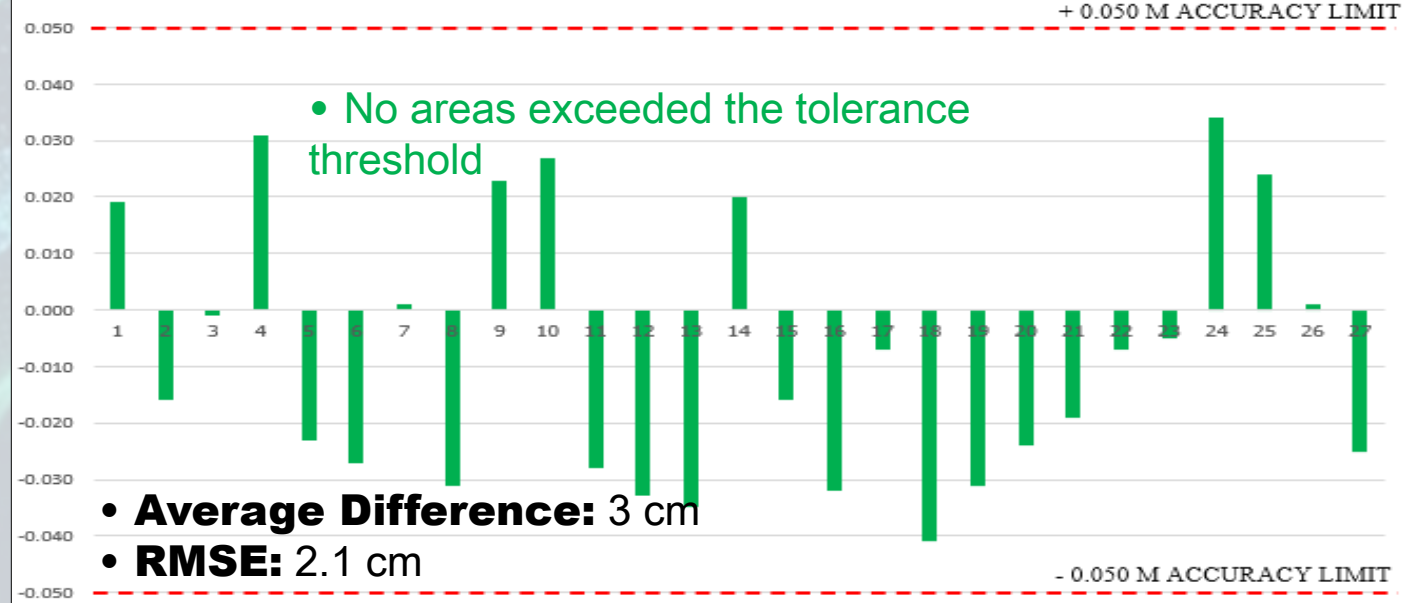
divided the volume difference by the survey area



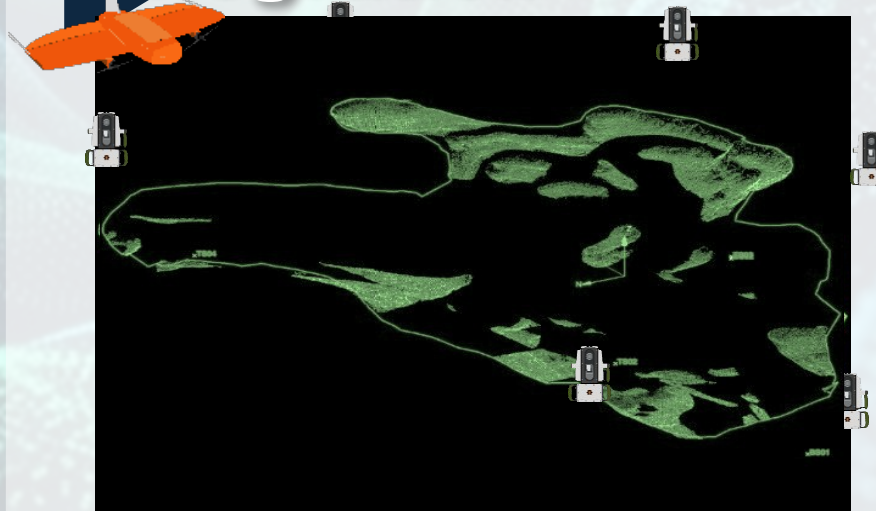
< ±5

equivalent
elevation
difference

Accuracy Comparison with TLS 100% VS UAV+GCGP



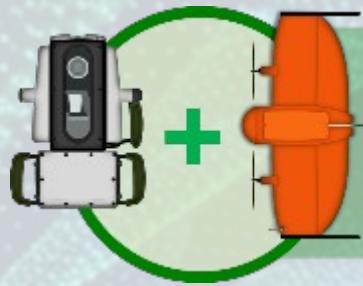
Hybrid Data Integration



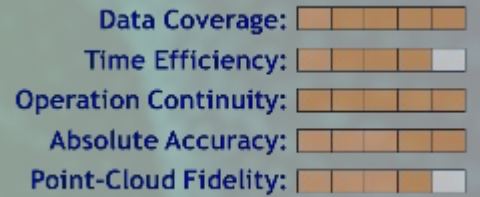
- **TLS** data is used where available
- **UAV** data is used selectively to "patch" gaps.

Conclusion

n



The result is reduced **operational downtime**, increased **safety**, and significantly enhanced **productivity**.



✓ **High Data Accuracy**
without relying on full laser scanning coverage.

✓ **Enhanced Safety**
Surveyors no longer need to enter hazardous mine pits.



Feedback

We would appreciate your perspective on:

- The reliability of this approach
- Potential **limitations or risks** in practical implementation



Share your perspectives!

Expectation



Thank you



EGAT

Electricity Generating Authority of Thailand